



Control Theory for Linear Systems (Communications and Control Engineering)

Harry L. Trentelman, Anton A. Stoorvogel, Malo Hautus

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Control Theory for Linear Systems deals with the mathematical theory of feedback control of linear systems. It treats a wide range of control synthesis problems for linear state space systems with inputs and outputs. The book provides a treatment of these problems using state space methods, often with a geometric flavour. Its subject matter ranges from controllability and observability, stabilization, disturbance decoupling, and tracking and regulation, to linear quadratic regulation, H₂ and H-infinity control, and robust stabilization. Each chapter of the book contains a series of exercises, intended to increase the reader's understanding of the material. Often, these exercises generalize and extend the material treated in the regular text.



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